

Review. Every **homogeneous linear first-order DE** can be written as $y' = a(x)y$.

Its general solution is $y(x) = Ce^{\int a(x)dx}$.

Comment. Note that the constant of integration can be absorbed into the factor C (in other words, there is only one degree of freedom in the above formula for the general solution).

Example 17. Solve $y' = x^2y$.

Solution. This is a homogeneous linear first-order DE $y' = a(x)y$ with $a(x) = x^2$. Accordingly, the general solution is $y(x) = Ce^{\int a(x)dx} = Ce^{\int x^2dx} = Ce^{\frac{1}{3}x^3}$.

Comment. As noted above, the constant of integration gets absorbed into the factor C .

Comment. Alternatively, we can solve this DE via separation of variables (see earlier example).

Recall that, to find the general solution of the **inhomogeneous DE**

$$y' = a(x)y + f(x),$$

we only need to find a particular solution y_p .

Then the general solution is $y_p + Cy_h$, where y_h is any solution of the homogeneous DE $y' = a(x)y$.

Comment. In applications, $f(x)$ often represents an external force. As such, the inhomogeneous DE is sometimes called “driven” while the homogeneous DE would be called “undriven”.

Theorem 18. (variation of constants) $y' = a(x)y + f(x)$ has the particular solution

$$y_p(x) = c(x)y_h(x) \quad \text{with} \quad c(x) = \int \frac{f(x)}{y_h(x)} dx,$$

where $y_h(x) = e^{\int a(x)dx}$ is any solution to the homogeneous equation $y' = a(x)y$.

Proof. Let us plug $y_p(x) = y_h(x) \int \frac{f(x)}{y_h(x)} dx$ into the DE to verify that it is a solution:

$$y'_p(x) = y'_h(x) \int \frac{f(x)}{y_h(x)} dx + y_h(x) \underbrace{\frac{d}{dx} \int \frac{f(x)}{y_h(x)} dx}_{\frac{f(x)}{y_h(x)}} = a(x)y_h(x) \int \frac{f(x)}{y_h(x)} dx + f(x) = a(x)y_p(x) + f(x) \quad \square$$

Comment. Note that the formula for $y_p(x)$ gives the general solution if we let $\int \frac{f(x)}{y_h(x)} dx$ be the general antiderivative. (Think about the effect of the constant of integration!)

Recall. The formula for $y_p(x)$ can be found using **variation of constants** (sometimes called variation of parameters): that is, we look for solutions of the form $y(x) = c(x)y_h(x)$.

If we plug $y(x) = c(x)y_h(x)$ into the DE $y' = ay + f$, we find $c'y_h + cy'_h = acy_h + f$. Since $y'_h = ay_h$, this simplifies to $c'y_h = f$ or, equivalently, $c' = \frac{f}{y_h}$.

Hence, $c(x) = \int \frac{f(x)}{y_h(x)} dx$, which is the formula in the theorem.

Example 19. Solve $x^2y' = 1 - xy + 2x$, $y(1) = 3$.

Solution. Write as $\frac{dy}{dx} = a(x)y + f(x)$ with $a(x) = -\frac{1}{x}$ and $f(x) = \frac{1}{x^2} + \frac{2}{x}$.

$y_h(x) = e^{\int a(x)dx} = e^{-\ln x} = \frac{1}{x}$. (Why can we write $\ln x$ instead of $\ln|x|$? See comment below.) Hence:

$$y_p(x) = y_h(x) \int \frac{f(x)}{y_h(x)} dx = \frac{1}{x} \int \left(\frac{1}{x} + 2\right) dx = \frac{\ln x + 2x + C}{x}$$

Using $y(1) = 3$, we find $C = 1$. In summary, the solution is $y = \frac{\ln(x) + 2x + 1}{x}$.

Comment. Note that $x = 1 > 0$ in the initial condition. Because of that we know that (at least locally) our solution will have $x > 0$. Accordingly, we can use $\ln x$ instead of $\ln|x|$. (If the initial condition had been $y(-1) = 3$, then we would have $x < 0$, in which case we can use $\ln(-x)$ instead of $\ln|x|$.)

Comment. Observe how the general solution (with parameter C) is indeed obtained from any particular solution (say, $\frac{\ln x + 2x}{x}$) plus the general solution to the homogeneous equation, which is $\frac{C}{x}$.